

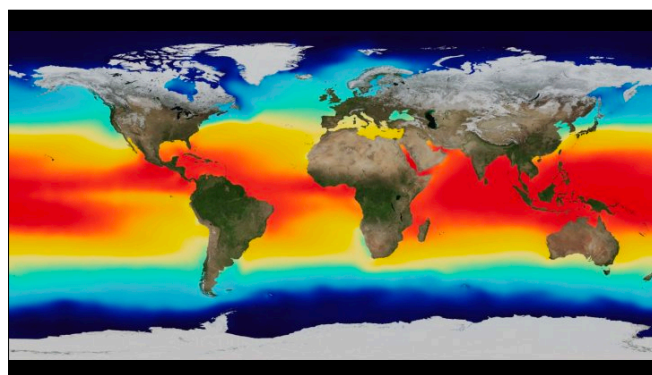
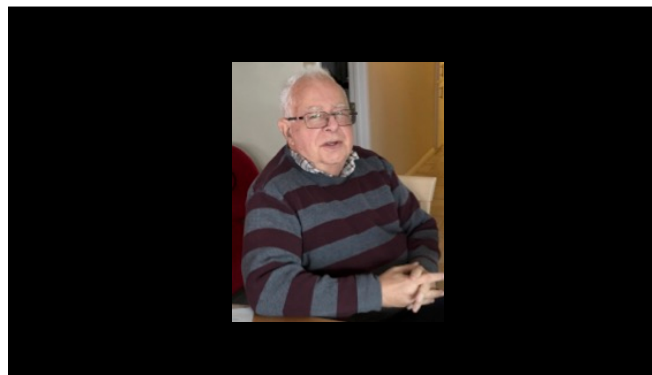
Touring world in

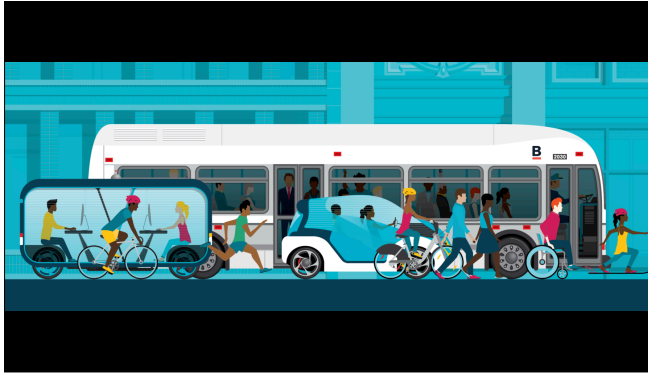
2050

Mark Pesce
www.markpesce.com
mark@markpesce.com
 Twitter: @mpesce



31 January 2050

 A podcast cover for "THE NEXT BILLION SECONDS WITH MARK PESCE". It features a portrait of Mark Pesce and text indicating he is the "AUSTRALIAN PODCAST AWARDS 2018 WINNER". The "podcastone" logo is at the bottom.




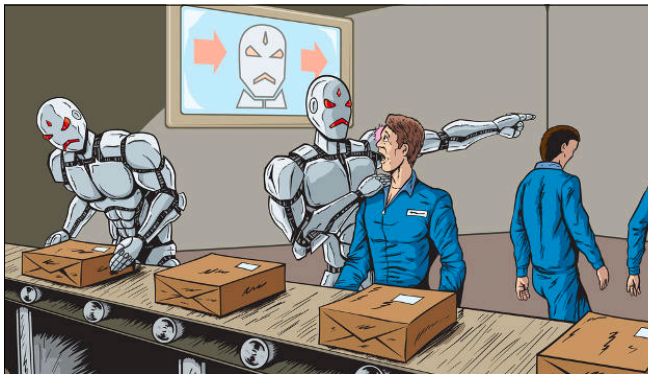
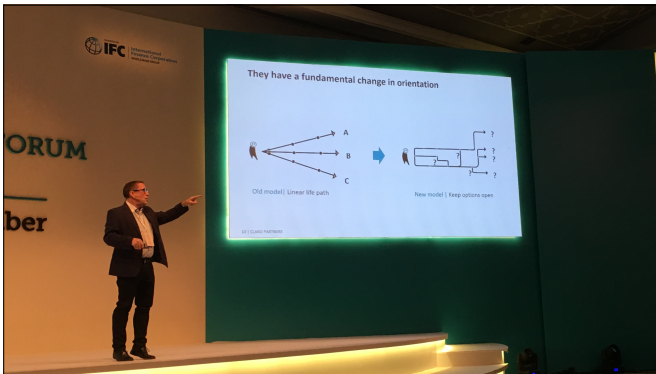
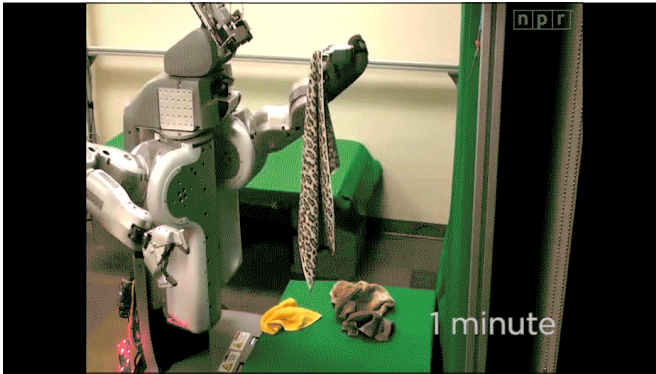
Uber in fatal crash detected pedestrian but had emergency braking disabled

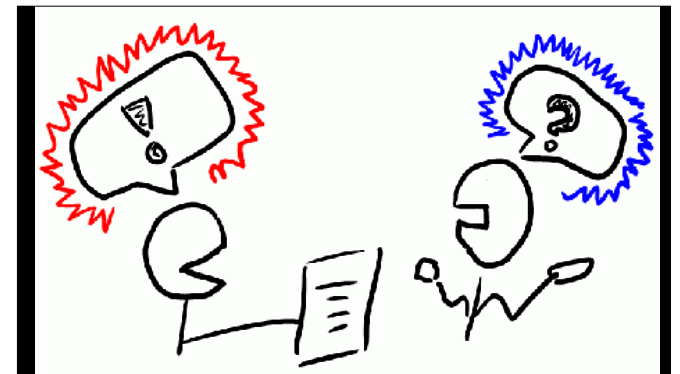
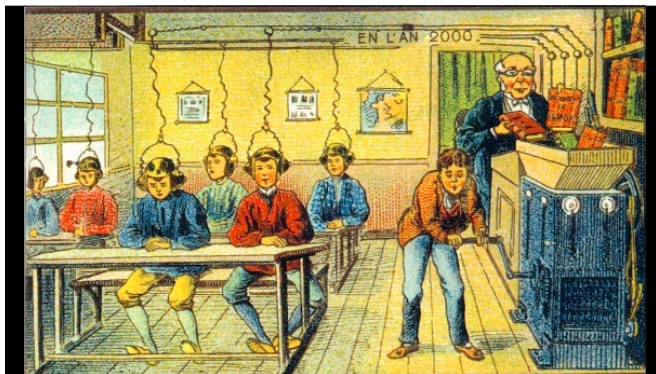
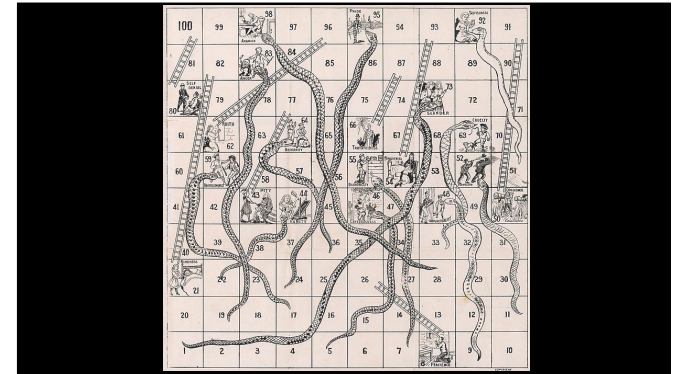
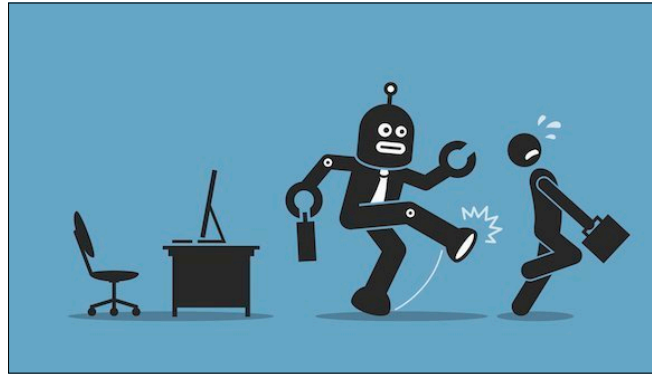
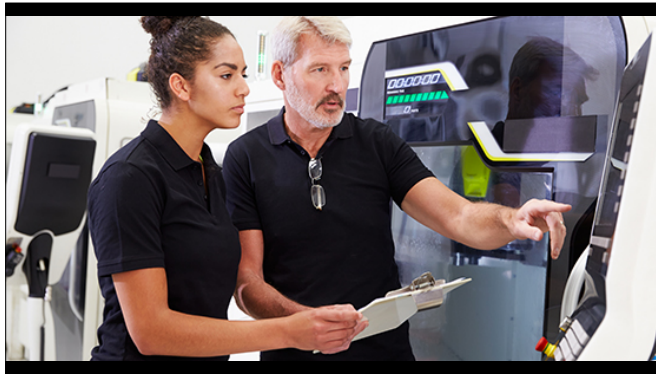
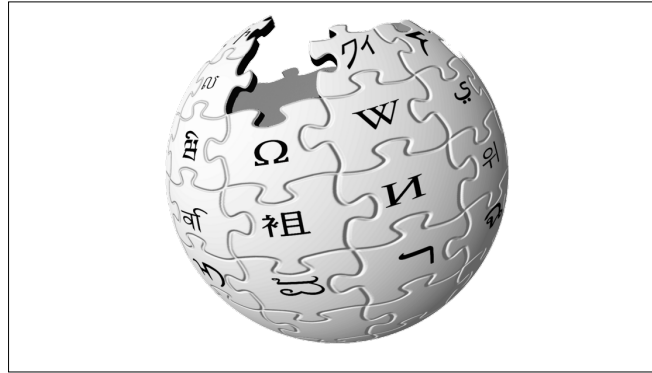
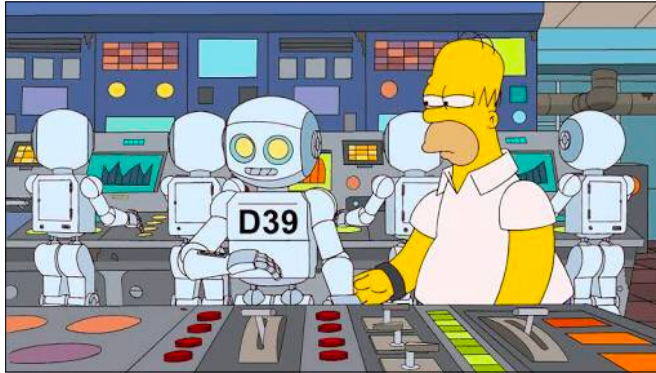
Devin Coldewey @techcrunch / 3 hours ago

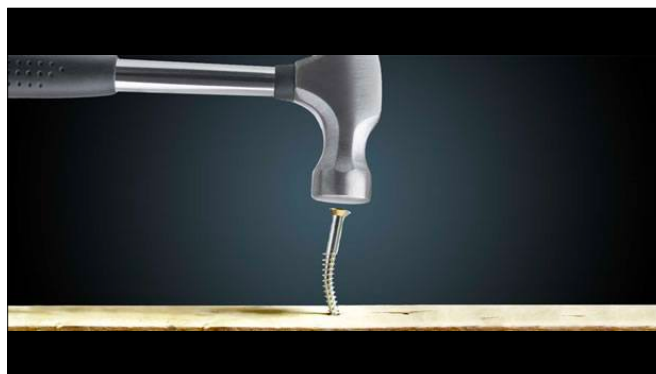
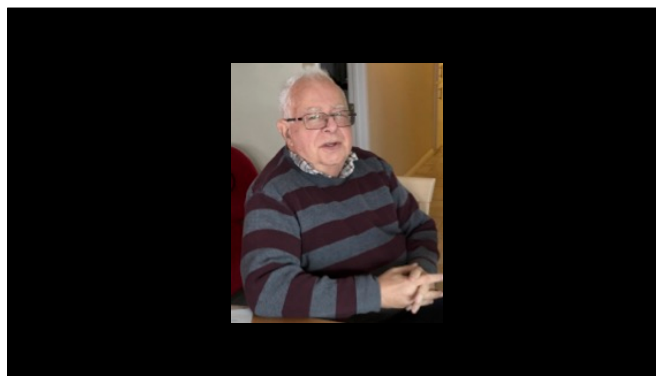
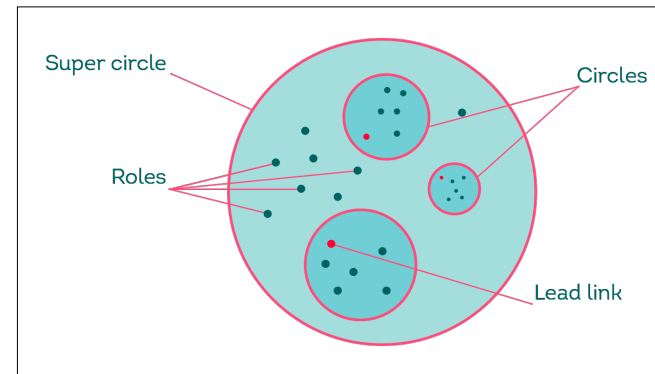
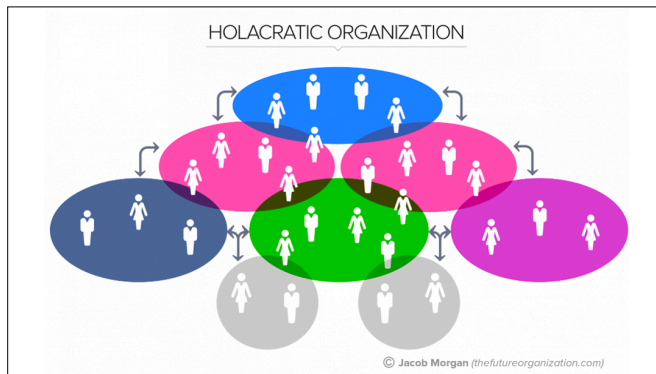
At 1.3 seconds before impact, the self-driving system determined that an emergency braking maneuver was needed to mitigate a collision. According to Uber, emergency braking maneuvers are not enabled while the vehicle is under computer control, to reduce the potential for erratic vehicle behavior. The vehicle operator is relied on to intervene and take action. The system is not designed to alert the operator.

Object detected as bicycle

The initial report by the National Transportation Safety Board on the

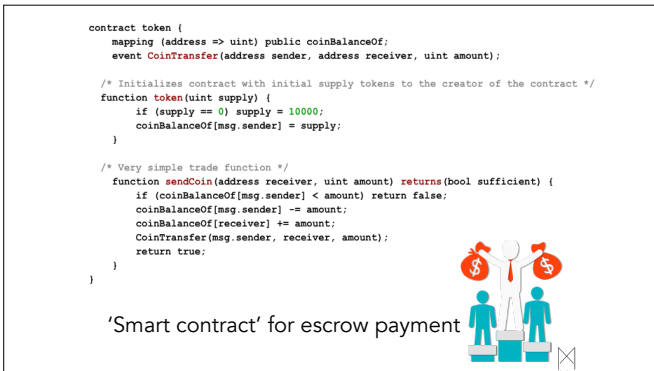
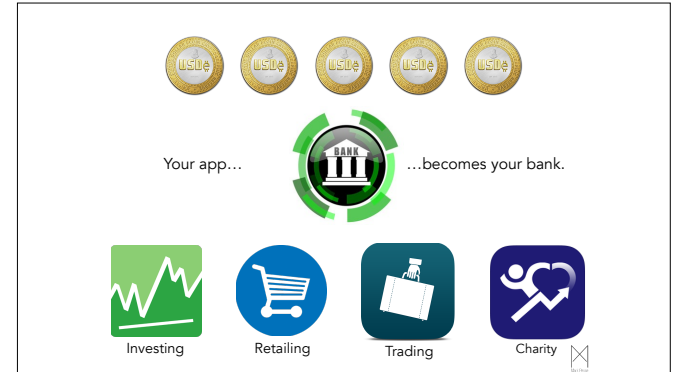
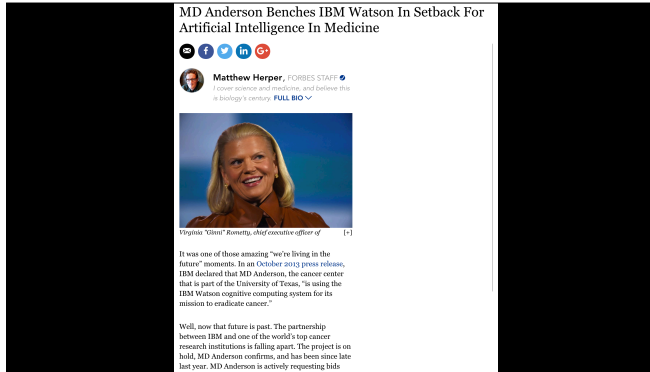
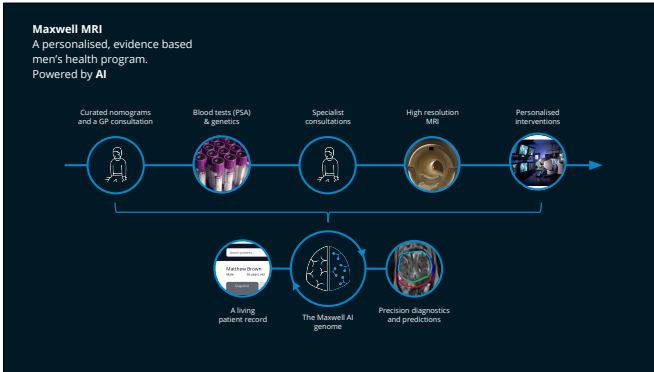
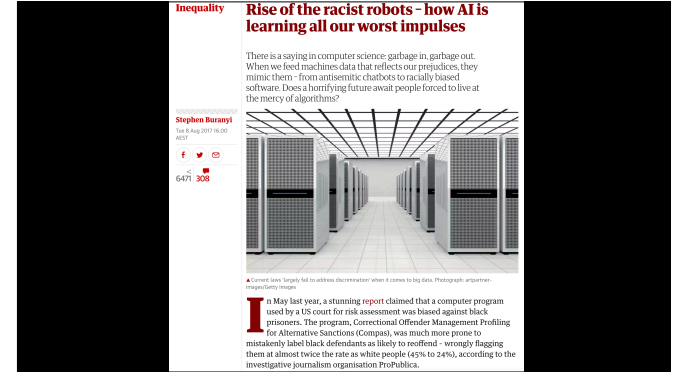
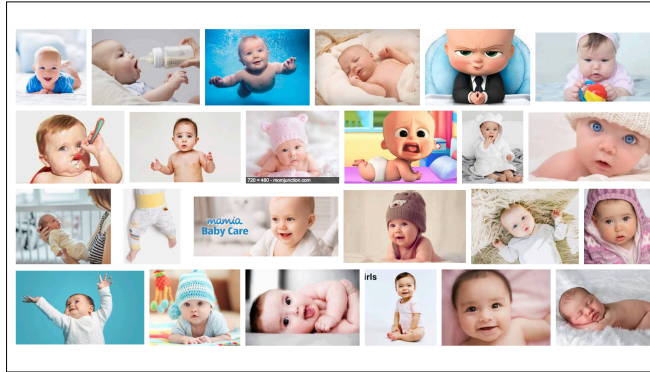
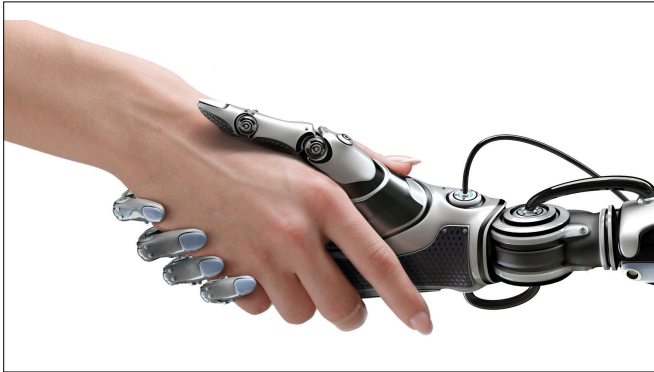
A diagram illustrating a vehicle's sensor range. A white car is shown on a road, with yellow arcs representing its field of vision or sensor range. A red dot on the road is labeled 'Object detected as bicycle'. The arcs are labeled with numbers 10, 20, and 30, likely representing distance in feet or meters.





$$\begin{array}{r}
 041.66\dots \\
 6 \overline{) 250} \\
 \underline{-24} \\
 10 \\
 \underline{-6} \\
 40 \\
 \underline{-36} \\
 40 \\
 \underline{-36} \\
 4 \dots
 \end{array}
 = 41.67$$

with How to Do Long Division





Thank you!



+61 418 653 187

mpesce@gmail.com

<https://www.markpesce.com>